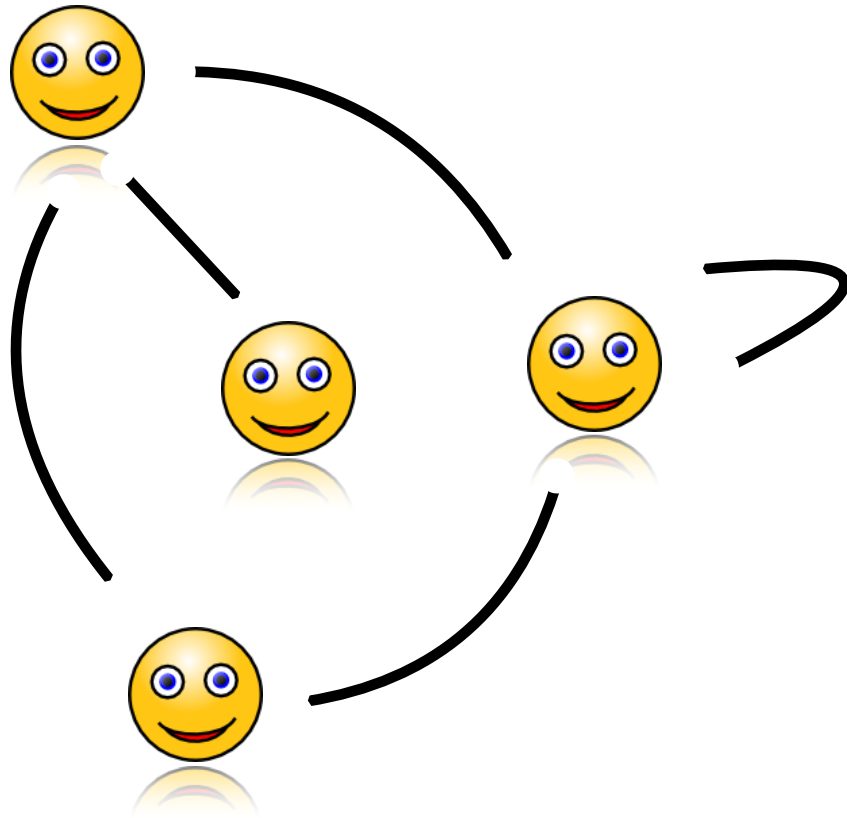


# A distributed abstract machine

*Computing with Collaborative Side Effects*

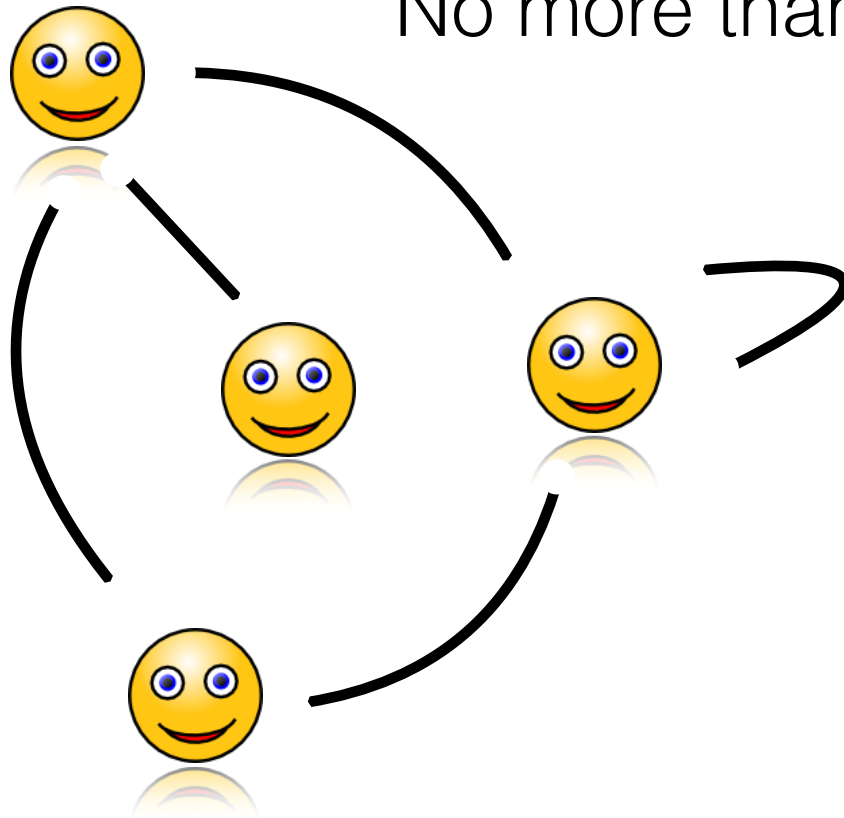
# The machine

# Graph



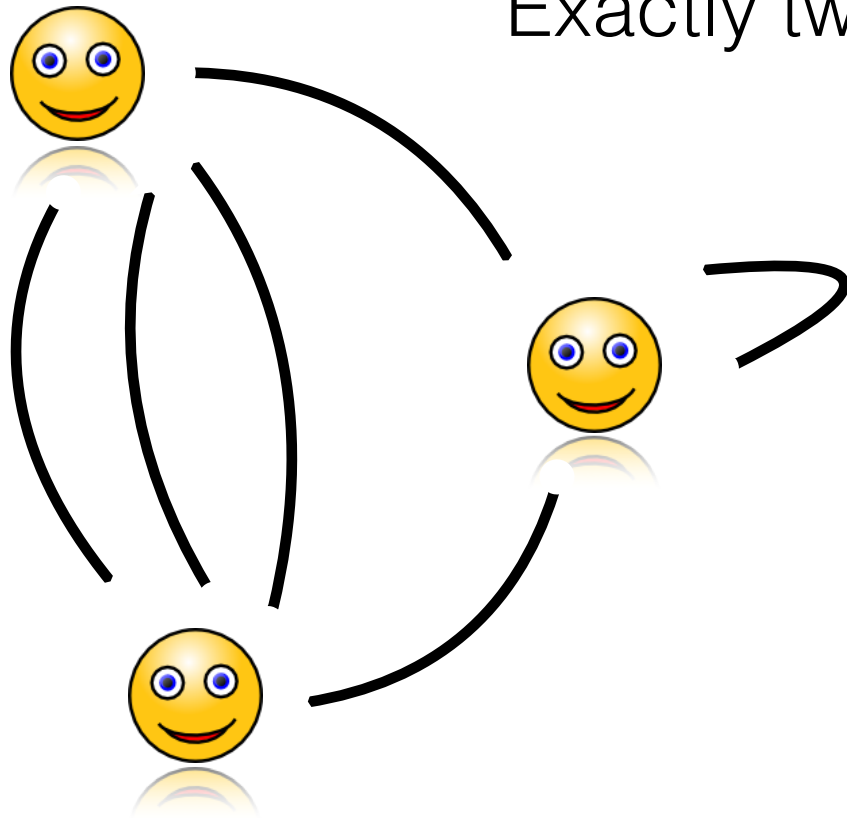
# Limit of successors

No more than two successors

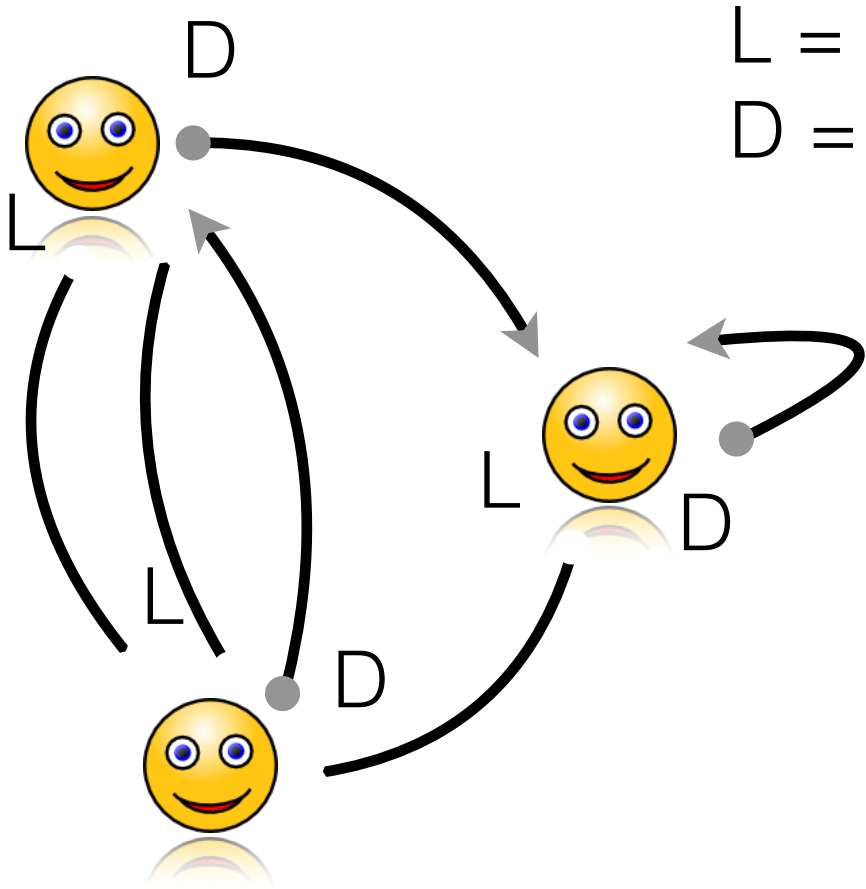


# binary graph

Exactly two successors



# Naming the two successors



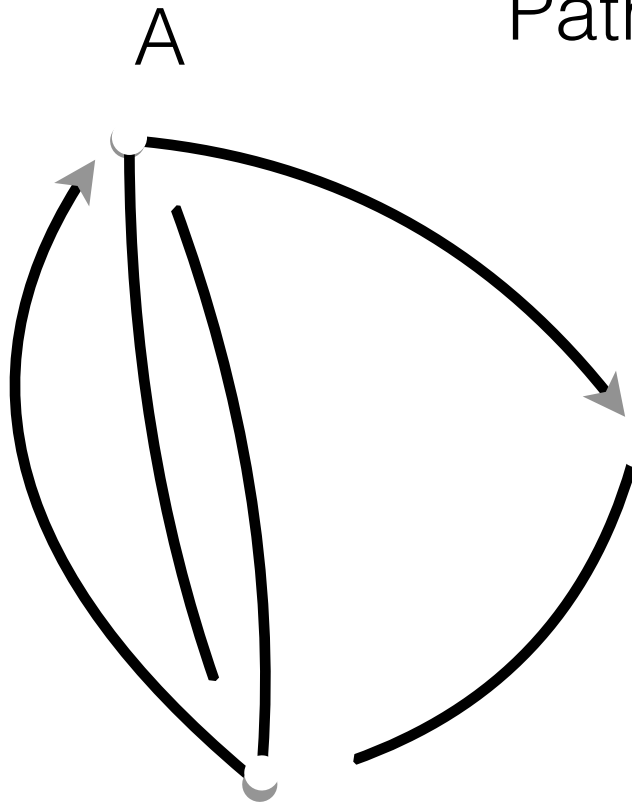
L = Light/Left  
D = Dark/Derecho/cDr

A binary tree without leaves

Node  $\triangleq$  Node x Node

# Paths

Path : follow one or more edges



$$\Delta = (L \mid D)^* = \delta^*$$

Node x Path  $\rightarrow$  Node

$$A \times DDDLL \rightarrow A$$

$$A \times LD \rightarrow A$$

# Instructions

If  $x$  is the central node, we want to do  $x.D = x.D.D$

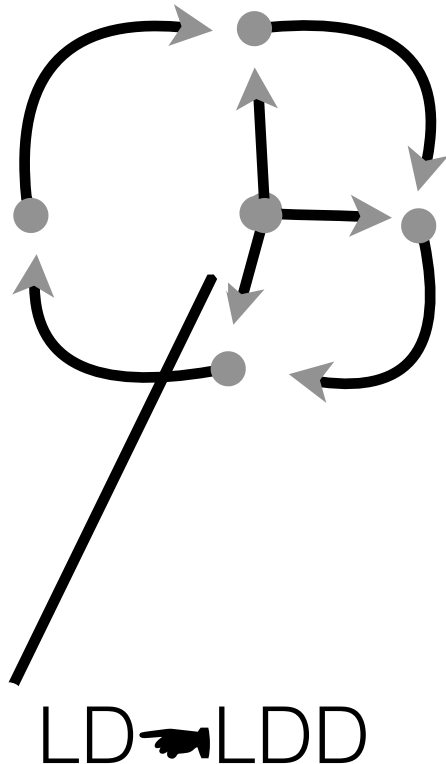
If  $x$  execute this instruction :  $this.D = this.D.D$

We simplify with  $D \rightarrow DD$

$\text{Instr} \triangleq \Delta \rightarrow \Delta$

Only one fixed instruction per node

When instructions are applied ?

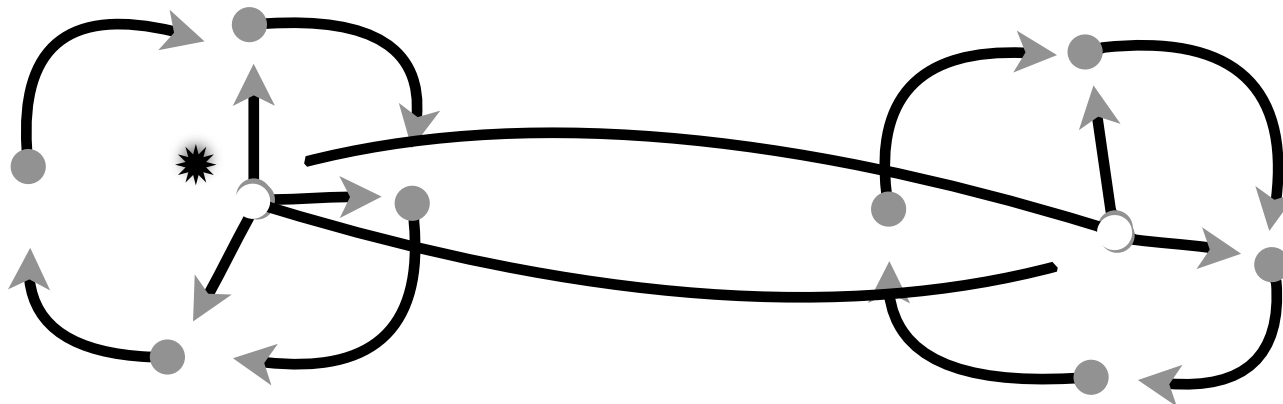




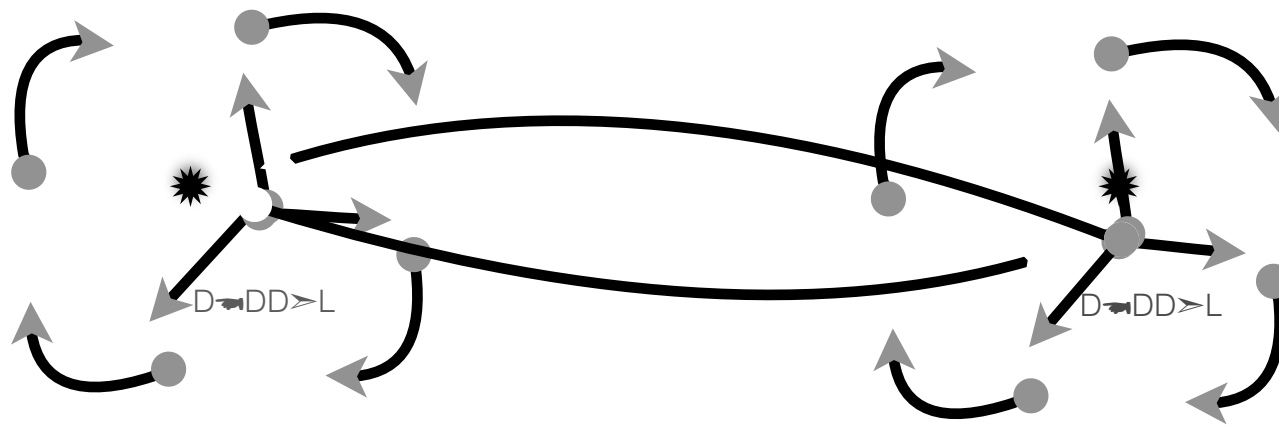
# Tokens

Instruction is executed when a node receive a token. The token is given to an another node after execution

Instr  $\triangleq$  D  DD  $\triangleright$  L



# More tokens



Property: number of nodes, edges and tokens are preserved by execution

# The machine

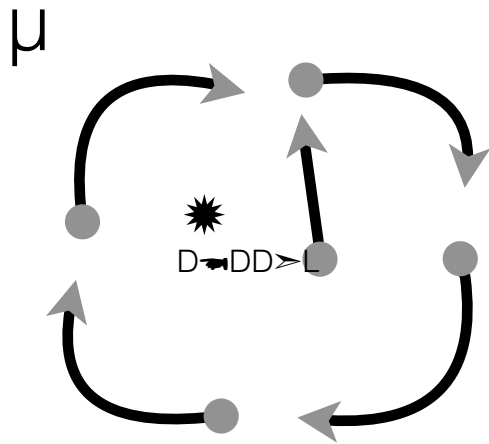
$l \in \text{Label}$      *a memory adress, an IP adress, ...*

$\Delta \in \text{Path} \triangleq (L \mid D)^*$

$c \in \text{Instr} \triangleq \text{Path} \xrightarrow{\quad} \text{Path} \triangleright \text{Path}$

$\text{Node} \triangleq \text{Nat} \times \text{Label} \times \text{Label} \times \text{Instr}$

$\mu \in \text{Mach} \triangleq \text{Label} \rightarrow \text{Node}$



$\mu(l_0) = \langle 1, l_0, l_1, D \xrightarrow{\quad} DD \triangleright L \rangle$

$\mu(l_1) = \langle 0, l_1, l_2, L \xrightarrow{\quad} L \triangleright L \rangle$

$\mu(l_2) = \langle 0, l_2, l_3, L \xrightarrow{\quad} L \triangleright L \rangle$

$\mu(l_3) = \langle 0, l_3, l_4, L \xrightarrow{\quad} L \triangleright L \rangle$

$\mu(l_4) = \langle 0, l_4, l_1, L \xrightarrow{\quad} L \triangleright L \rangle$

# Sequential semantics

# Following a path

$\mathcal{F} : \text{Mach} \times \text{Label} \times \text{Path} \rightarrow \text{Label}$

$$\mathcal{F}(\mu, l, []) = l$$

$$\frac{\mu(l) = \langle n, l_L, l_D, C \rangle}{\mathcal{F}(\mu, l, L \cdot \Delta) \rightarrow \mathcal{F}(\mu, l_L, \Delta)}$$

$$\frac{\mu(l) = \langle n, l_L, l_D, C \rangle}{\mathcal{F}(\mu, l, D \cdot \Delta) \rightarrow \mathcal{F}(\mu, l_D, \Delta)}$$

# Node access

$f[x \leftarrow v] \triangleq \lambda y. \text{if } y=x \text{ then } v \text{ else } (f y)$

$$\frac{\mu(l) = \langle n+1, l', l'', c \rangle}{(\text{decreaseToken } \mu \ l) = \mu[l \leftarrow \langle n, l', l'', c \rangle]}$$

$$\frac{\mu(l) = \langle n, l', l'', c \rangle}{(\text{increaseToken } \mu \ l) = \mu[l \leftarrow \langle n+1, l', l'', c \rangle]}$$

$$\frac{\mu(l) = \langle n, l', l'', c \rangle}{(\text{changeField } \mu \ l \ L \ v) = \mu[l \leftarrow \langle n, v, l'', c \rangle]}$$

# rules for machine transition

Mach  $\rightarrow$  Mach

$$\mu(l) = \langle n+1, l_L, l_D, \Delta_d \cdot \delta \rightarrow \Delta_s \triangleright \Delta_n \rangle$$

$$\mu' = (\text{decreaseToken } \mu \ l)$$

$$\mu'' = (\text{changeField } \mu' \ \mathcal{F}(\mu, l, \Delta_d) \ \delta \ \mathcal{F}(\mu, l, \Delta_s))$$

$$\mu''' = (\text{increaseToken } \mu'' \ \mathcal{F}(\mu, l, \Delta_n))$$

---

$$\mu \rightarrow \mu'''$$

# Turing completeness



# Compiling SECD to the Distributed Abstract Machine

S(tack) *A stack of values*

E(nv) *A list of values*

C(ode) *A list of instructions*

D(ump) *A list of frames*

S(tack)

A(ux) *A register*

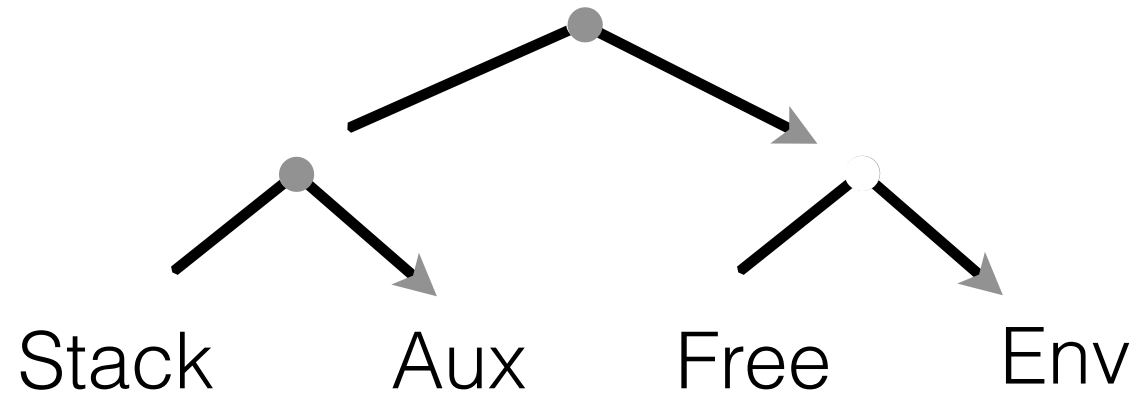
F(ree) *A free list*

E(nv)

No Dump

The code is outside

# SAFE structure



**S**  $\triangleq$  LL

**A**  $\triangleq$  LD

**F**  $\triangleq$  DL

**E**  $\triangleq$  DD

# Code structure

$\Delta_d \rightarrow \Delta_s \rightarrow \Delta_n$



*The SAFE structure*

Almost all the time  $\Delta_n = D$

**S**  $\triangleq$  **LS**

**A**  $\triangleq$  **LA**

**F**  $\triangleq$  **LF**

**E**  $\triangleq$  **LE**

# SECD code to DAM

$$\llbracket \text{Code} \rrbracket_t \rightarrow t'$$

$t$  is the place where is the SAFE machine

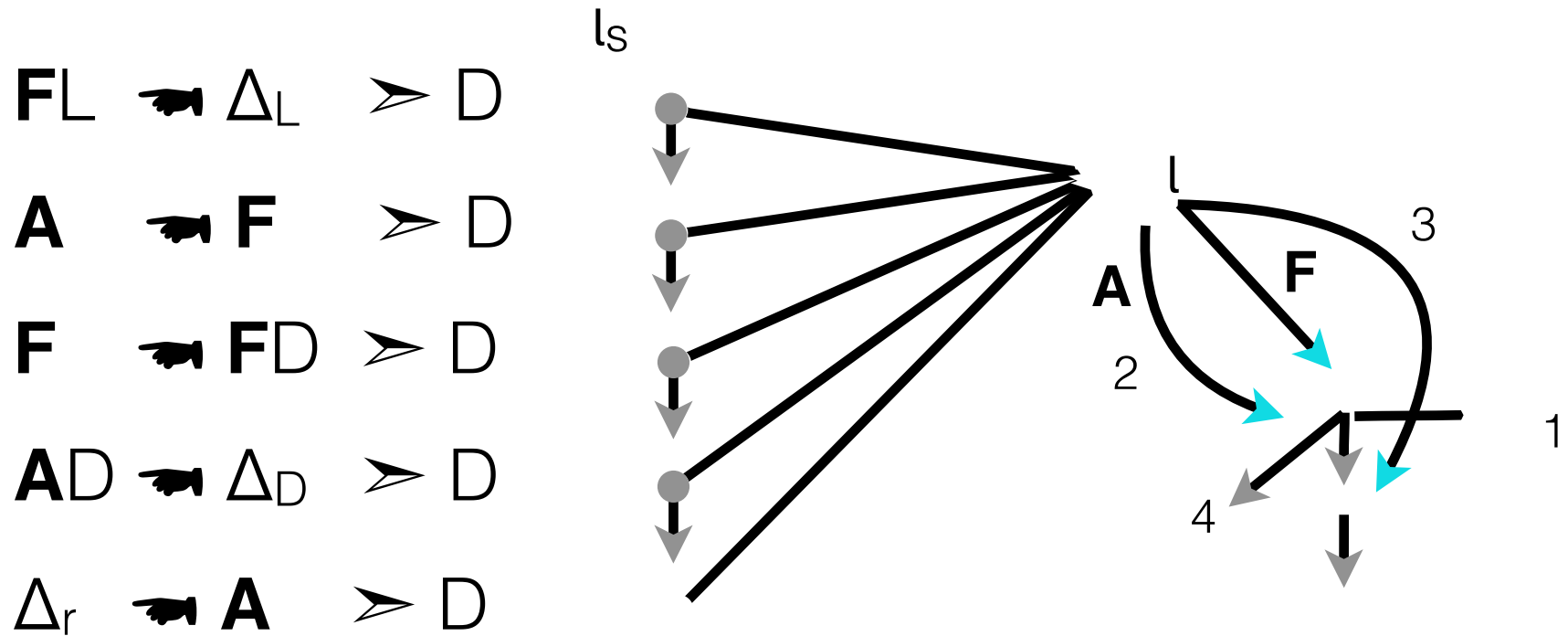
$t'$  is the result in a form of a list linked by their dark field

$$\llbracket \text{nil} \rrbracket_t \rightarrow \langle \text{some stop} \rangle$$

$$\llbracket i . c \rrbracket_t \rightarrow \llbracket i \rrbracket_t \bullet \llbracket c \rrbracket_t$$

# Allocation

$$\text{Alloc}(l, \Delta_L, \Delta_D, \Delta_r) \rightarrow l_s$$



A may be  $\Delta_L$  or  $\Delta_r$  but not  $\Delta_D$

# Access to a variable

Interpretation inside the SECD machine

$$\langle s, e, (\mathbf{ld} \ i) \cdot c, d \rangle \rightarrow \langle (\text{get } e \ i) \cdot s, e, c, d \rangle$$

Compilation to the DAM machine

$$\llbracket (\mathbf{ld} \ i) \rrbracket_l \rightarrow \text{Alloc}(l, \mathbf{E} \cdot D^i \cdot L, \mathbf{S}, \mathbf{S})$$

# Closures

Interpretation inside the SECD machine

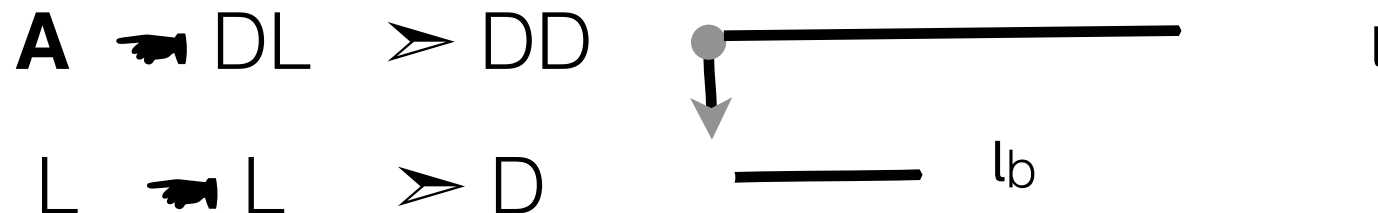
$$\langle s, e, (\mathbf{ldf} \ c_f) \cdot c, d \rangle \rightarrow \langle \langle c_f \ e \rangle \cdot s, e, c, d \rangle$$

Compilation to the DAM machine

$$\llbracket (\mathbf{ldf} \ c_f) \rrbracket_l \rightarrow \text{movAux}(l, \llbracket c_f \rrbracket_l)$$

- Alloc( $l, \mathbf{A}, \mathbf{E}, \mathbf{A}$ )
- Alloc( $l, \mathbf{A}, \mathbf{S}, \mathbf{S}$ )

movAux( $l, l_b$ )



# Application

Interpretation inside the SECD machine

$$\langle a \cdot \langle c_f \ e_f \rangle \cdot s, e, \mathbf{app} \cdot c, d \rangle \rightarrow \langle [], a \cdot e_f, c_f, \langle s, e, c \rangle \cdot d \rangle$$

Compilation to the DAM machine

$$\llbracket \mathbf{app} \rrbracket_l \rightarrow \text{Alloc}(l, \mathbf{SL}, \mathbf{SDLD}, \mathbf{A}) \bullet \text{app}(l)$$

		app(l)		
		S	E	A
<b>SL</b>	→ <b>E</b>			
<b>E</b>	→ <b>A</b>			
<b>SDL</b>	→ <b>D</b>			
	→ <b>SDLL</b>			



# Return

Interpretation inside the SECD machine

$$\langle r \cdot s', e', \mathbf{ret} \cdot c', \langle s, e, c \rangle \cdot d \rangle \rightarrow \langle r \cdot s, e, c, d \rangle$$

Compilation to the DAM machine

$$\llbracket \mathbf{ret} \rrbracket_l \rightarrow \text{return}(l)$$

return(l)

S	E

**E**  $\rightarrow$  **SDL**  $\triangleright$  **D**

**SD**  $\rightarrow$  **SDDD**  $\triangleright$  **SDDL**

# Micro coded machine

Many sequences of node are identical

Sharing by putting some code inside the machine

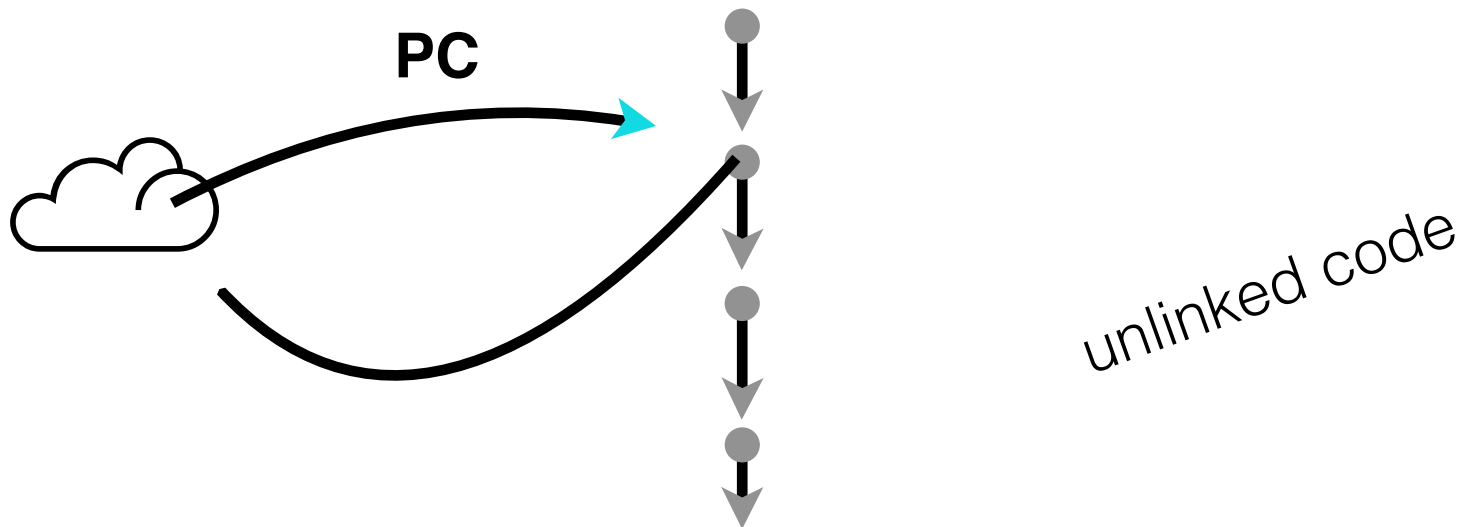
**S**  $\triangleq$  ...       $\llbracket (\text{Ld } i) \rrbracket_t \rightarrow \mathbf{A} \rightarrow \mathbf{E} \cdot \mathbf{D}^i \cdot \mathbf{L} \triangleright \mathbf{Ld}$       **Ld**  $\triangleq$  ...  
**A**  $\triangleq$  ...      **Ldf**  $\triangleq$  ...  
**F**  $\triangleq$  ...      **App**  $\triangleq$  ...  
**E**  $\triangleq$  ...      **Ret**  $\triangleq$  ...

*But we have loose  
the continuation*

# Unlinked code

All the instructions have a static link to the machine

Let's the machine to install itself before running



# Micro-sequenser

*Install the machine and goto the instruction*

**(Fetch)** **PCL**  $\rightarrow$   $\langle m \rangle$   $\triangleright$  **D**

**K**  $\rightarrow$  **PCD**  $\triangleright$  **PC**

*User instruction*

**A**  $\rightarrow$  **E·Di·L**  $\triangleright$  **Ld**

*Micro code*

**(Ld)** Alloc(*l*, **E·Di·L**, **S**, **S**) • (**L**  $\rightarrow$  **L**  $\triangleright$  **Next**)

*Epilogue*

**(Next)** **PCL**  $\rightarrow$  **PC**  $\triangleright$  **D**

**PC**  $\rightarrow$  **K**  $\triangleright$  **Fetch**

# Closures

*User instruction*

**A**  $\rightarrow$  DL  $\triangleright$  **Ldf**  $\downarrow$   
L  $\rightarrow$  L  $\triangleright$  D — lb

*Micro code*

- (Ldf)**
- Alloc(<m>, **A**, **E**, **A**)
  - Alloc(<m>, **A**, **S**, **S**)
  - (**K**  $\rightarrow$  **KD**  $\triangleright$  **Next**)

# Application

*User instruction*

L  $\rightarrow$  L  $\triangleright$  **App**

*Micro code*

Alloc(<m>, **SL**, **SDLD**, **A**)

**(App)**

• **SL**  $\rightarrow$  **E**  $\triangleright$  D

• **E**  $\rightarrow$  **A**  $\triangleright$  D

• **K**  $\rightarrow$  **SDLL**  $\triangleright$  D

• **SDL**  $\rightarrow$  **PCD**  $\triangleright$  **Next**







# Return

*User instruction*

L  L  **Ret**

*Micro code*

**(Ret)**

- E**  **SDL**  **D**
- **K**  **SDLL**  **D**
- **SD**  **SDDD**  **Next**

# Exercise

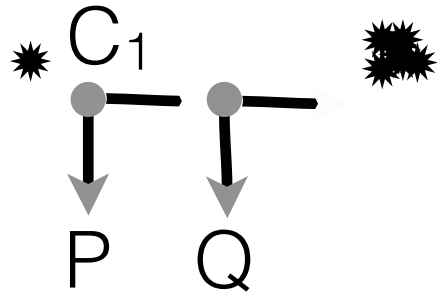
Do the AppRet micro-code  
compiled for a tail call



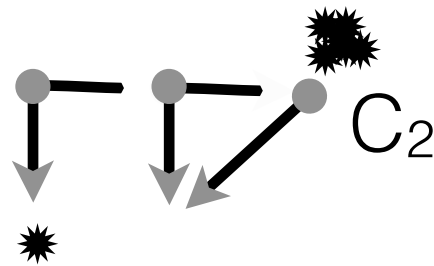
# Synchronisation patterns

# Parallelism = token generation

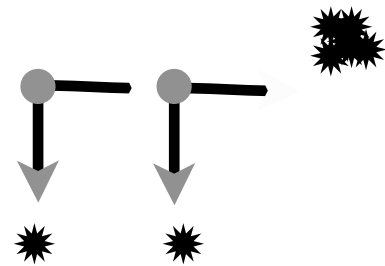
$$\llbracket (P \parallel Q) \rrbracket \rightarrow \text{par}(\llbracket P \rrbracket, \llbracket Q \rrbracket) \quad \text{⊗}$$



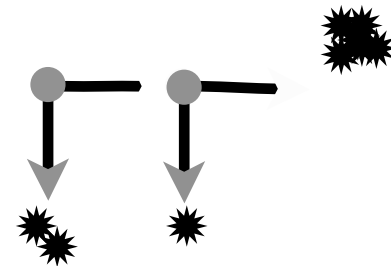
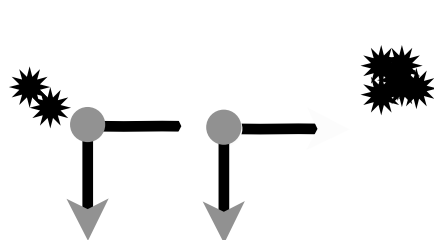
$$C_1 \triangleq \text{LLD} \rightarrow \text{LD} \triangleright D$$



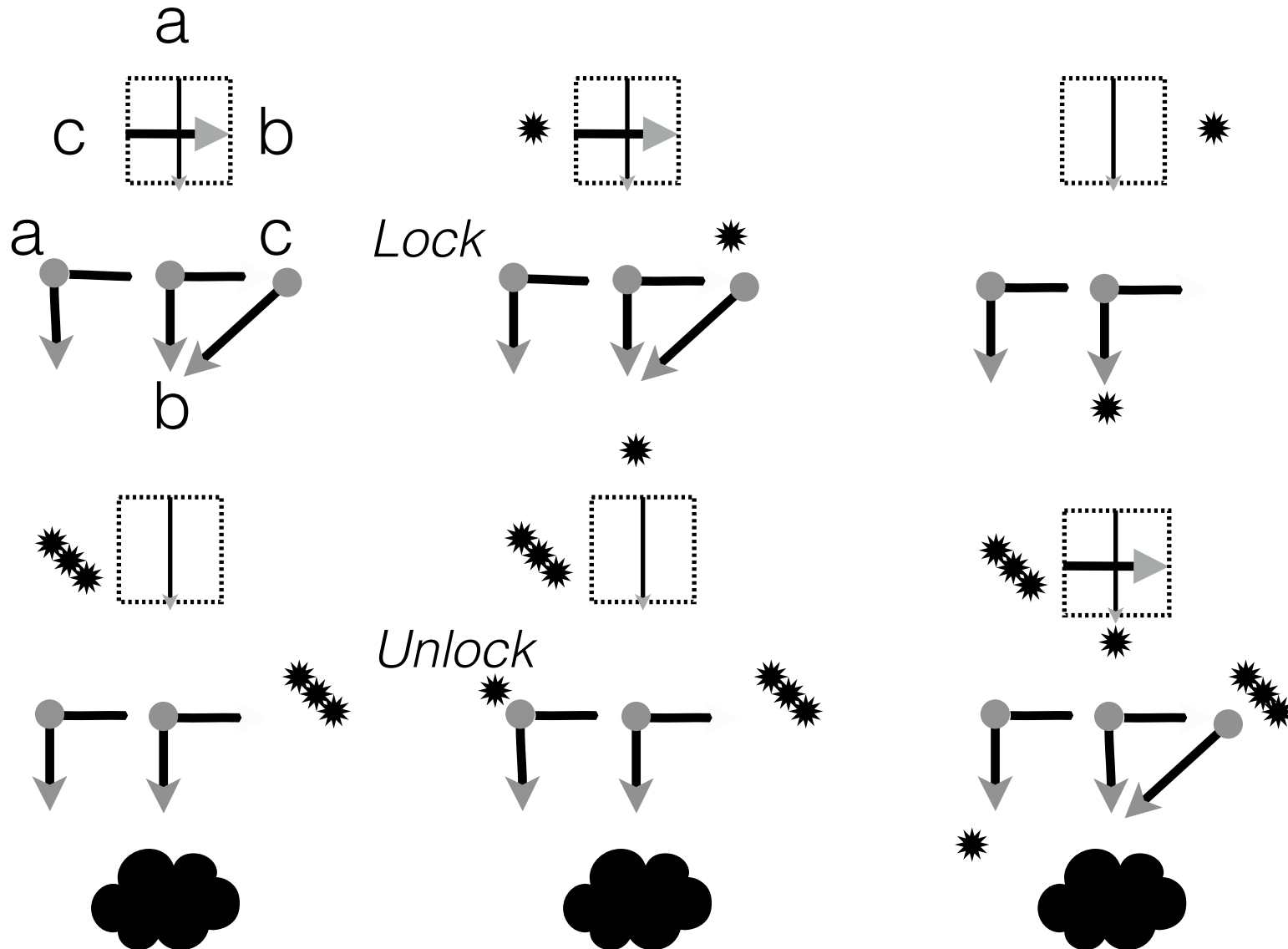
$$C_2 \triangleq D \rightarrow L \triangleright D$$



*Must be synchronised*

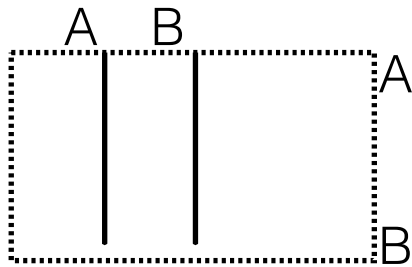
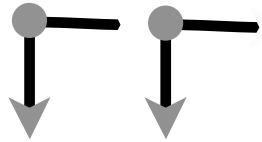


# mutex = token retention

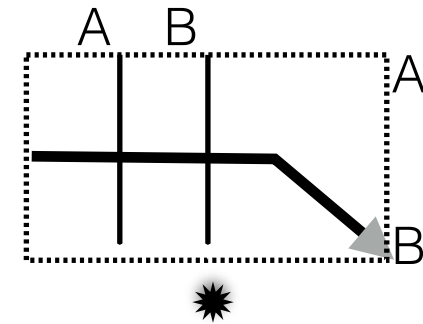
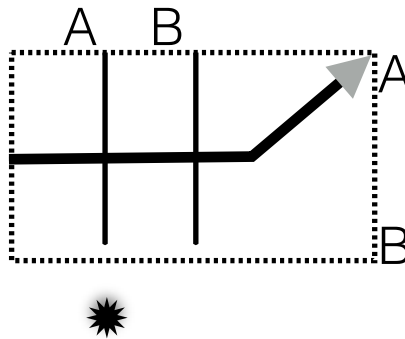
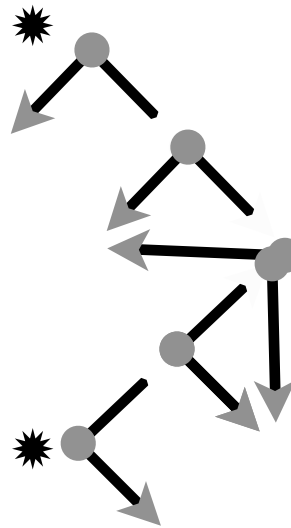


# Multiple entries mutex

1 entry



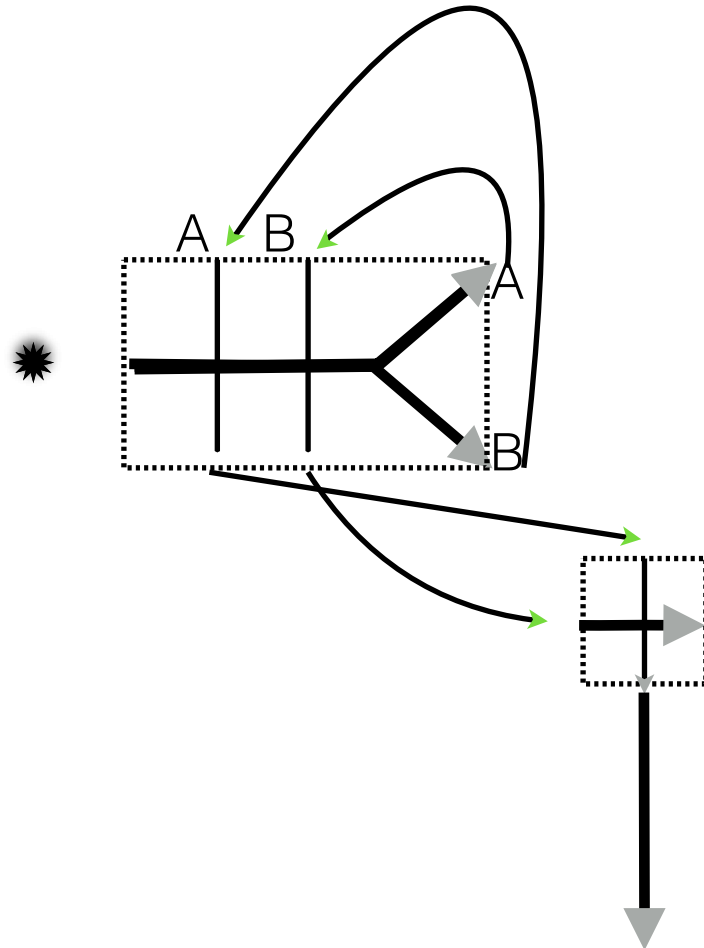
2 entries





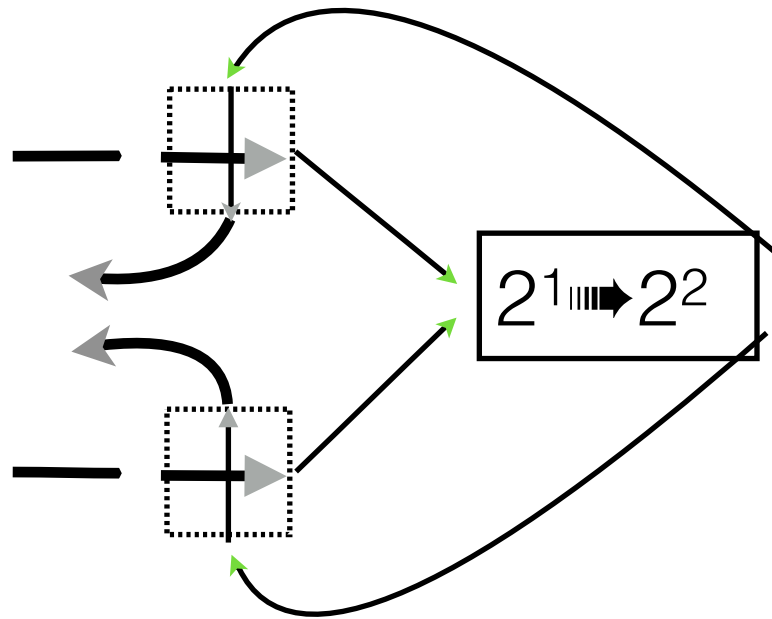
# Bad implementation of

$$2^1 \rightsquigarrow 2^2$$



# Synchronisation

Waiting 2 tokens on two nodes =  $2^2 \dashv\vdash 2^2$

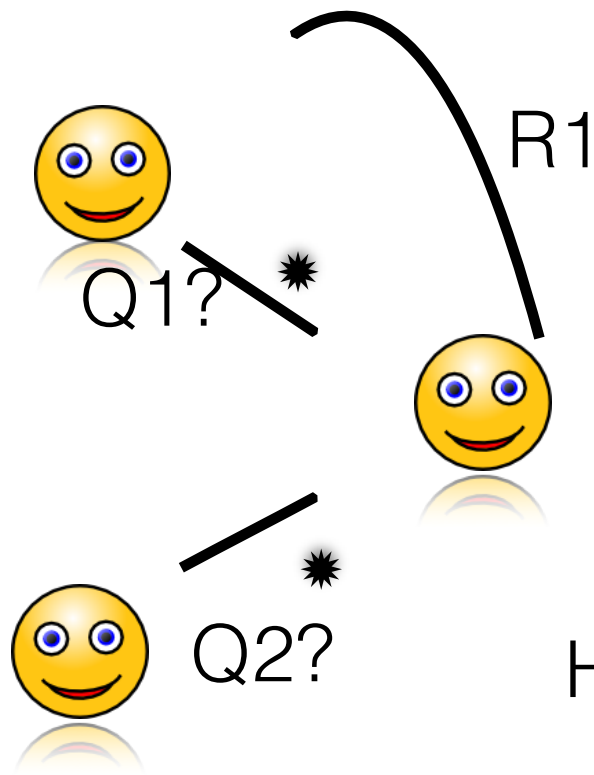


Not enough for CCS :  
the continuations are  
static

# Call convention



# Concurrent call convention



Callers must give their arguments at a specific place of the callee

Cannot lock a mutex and write a data at the same node (2 writes)

Having values associated to tokens is a solution. Is it essential ?

# Wrong protocol

## ***Caller Side***

- 1 Me.Cont = @4
- 2 Callee.Caller = Me
- 3 Send the token to Callee
- 4 *Me.Resp is OK*

- 1' Me'.Cont = @4'
- 2' Callee.Caller = Me'
- 3' Send the token to Callee
- 4' *Me'.Resp is OK*

## ***Callee Side***

- 1 Close the door
- 2 Caller.Resp = f(Caller)
- 3 Give a token to Caller.Cont
- 4 Open the door
- 5 Stop

*2 and 2' are  
concurrent writes*

# spinlock / polling ?

- 1 Me.Run = true
- 2 Me.Cont = @7
- 3 Callee.Caller = Me
- 4 Give a token to Callee
- 5 While Me.Run  
    Callee.Caller = Me
- 6 Stop
- 7 *Me.Resp is OK*

- 5' While Me'.Run  
    Callee.Caller = Me'

- 1 Close
- 2 C=Caller
- 3 C.Run = false
- 4 C.Resp = f(C)
- 5 Open > C.Cont

*After Callee@5, Callee.Caller  
may still have Me instead of  
Me' (for 2 reasons)*

# Waiting caller inactivity

- 1 Me.Wait = @4
- 2 Callee.Caller = Me
- 3 Give a token to Callee
- 4 Callee.Caller = Me > Me.Wait
- 5 > Callee@4
- 6 *Me.Resp is OK*

- 1 Close
- 2 C=Caller
- 3 C.Wait = C@5 > Stop
- 4 C.Resp = f(C)
- 5 Open > C@6

# Waiting to caller's value

\* Me.Wait = @3  
2 Give a token to Callee \*  
3 Callee.Caller = Me > Me.Wait  
4 > Callee@5  
5 *Me.Resp is OK*

1 Close  
2 Caller==None ? 2 : 3  
3 C = Caller  
4 C.Wait = C@4 > Stop  
5 Caller=None  
6 C.Resp = f(C)  
7 Open > C@5

The first write in the caller can be removed

# None equality

## *All callers but None*

0 > Callee@3

1 ...

## *None*

0 > Callee@2

1 Close

2 > Caller@0

3 C = Caller

4 ...

Can we replace 2&3 with C = Caller > Caller@0 ?

# Asynchronous Semantics

Incorporating the path following in the rules

# New structure

$\mu \in \text{Mach} \triangleq \text{Label} \rightarrow \text{Node}$

$\text{Node} \triangleq \text{Tokens: Nat} \times \text{L: Label} \times \text{D: Label} \times \text{Code: Instr}$   
 $\times \text{Values: (Path} \times \text{Label)}^3$   
 $\times \text{SetJumps: } \mathcal{P}(\text{Edge} \times \text{Label} \times \text{Label})$

Values will contain the intermediate values of the 3 follow (**F**) calls in the sequential semantics

Setjumps is a set of pending affectation that a node have to perform on one of its fields (denoted by the edge), the second label point to the node which have to receive a token



# Start

$$\mu(l)=n \quad \wedge \quad n.Tokens=t+1 \quad \wedge \quad n.SetJumps= \emptyset \\ \wedge \quad n.Code = \Delta_d \cdot \delta \rightarrow \Delta_s \rightarrow \Delta_n \quad \wedge \quad n.Values = ()$$

---

$$\mu \rightarrow \mu[l \leftarrow n[Tokens \leftarrow t][Values \leftarrow ((\Delta_{d,l})(\Delta_{s,l})(\Delta_{t,l}))]]$$

A node can start its execution only if it have at least one token, it have no pending writes and if it doesn't currently executing its instruction

To start, the node have only decrease the number of its tokens and initiate its *Values* field

No communication

# Following one edge

$$\frac{\mu(l)=n \wedge n.Values=(\dots(\delta.\Delta,l')\dots) \wedge \mu(l')=r \wedge r.\delta=l''}{\mu \rightarrow \mu[l \leftarrow n[Values \leftarrow (\dots(\Delta,l'')\dots)]]}$$

Field can be fetched with a message passing style

# SendWrite

$$\mu(l)=n \wedge n.Values=((\epsilon,l_d)(\epsilon,l_s)(\epsilon,l_t)) \wedge \mathbf{l_d \triangleleft l}$$

$$\wedge n.Code = \Delta_d \cdot \delta \rightarrow \Delta_s \triangleright \Delta_n \wedge \mu(l_d)=n_d$$

---


$$\mu \rightarrow \mu[l \leftarrow n[Values:=()]]$$

$$[l_d \leftarrow n_d[SetJumps \leftarrow n_d.SetJumps \cup \{(\delta,l_s,l_t)\}]]$$

When the path resolution is finish, the node transmit a message to the node which have to change its field. The label of the node which have to receive the token is included in the message

The token must be valid only after affectation

A node cannot send a message to itself

# SetJump

$$\mu(l)=n \wedge n.SetJumps=\{\delta, l_s, l_t\} \cup W \wedge n.Values = \emptyset$$

---

$$\mu \rightarrow \text{Jump}(l_t, \mu[l \leftarrow n[\delta \leftarrow l_s][SetJumps \leftarrow W]])$$

$$\text{Jump}(l, \mu) = \mu[l = \mu(l)[Tokens = 1 + \mu(l).Tokens]]$$

Jump increments the number of token of one specific node

A node can change one of its L or D fields only if it is not executing its instruction

# LocalWrite

$$\begin{aligned} & \mu(l)=n \quad \wedge \quad n.Values=((\epsilon,l)(\epsilon,l_s)(\epsilon,l_t)) \\ & \wedge n.Code = \Delta_d.\delta \rightarrow \Delta_s \rightarrow \Delta_n \end{aligned}$$

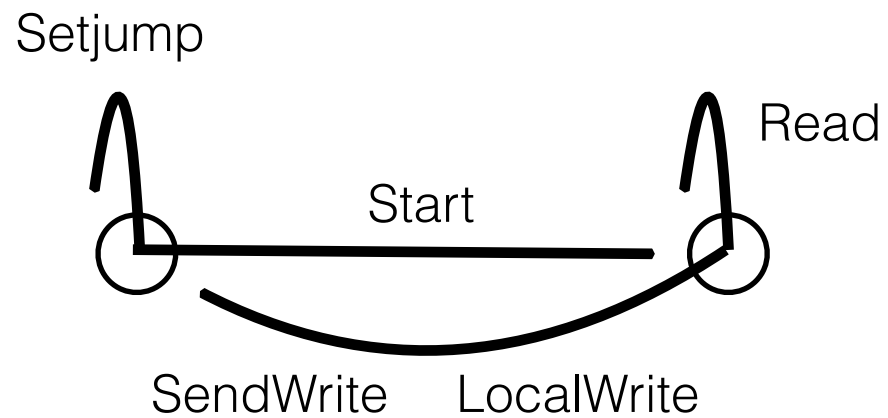
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$$\mu \rightarrow \text{Jump}(l_t, \mu[l \leftarrow n[\delta \leftarrow l_s][Values:=()]])$$

A local write must be done before all pending writes

Without the LocalWrite rule, mutex and token generation doesn't work

# Time life of a node



# The minimal instance

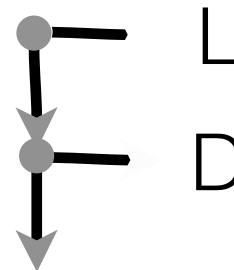
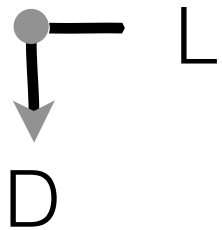
Could we bound the number of instructions ?

Simulating the path following by the machine itself

# Get extra memory

Add a node on every dark edge and compile the code on the fresh node

$$\Delta_d \cdot \delta \rightarrow \Delta_s \triangleright \Delta_n$$



$$\llbracket T(\Delta_d \cdot \delta) \rightarrow T(\Delta_s) \triangleright T(\Delta_n) \rrbracket_t$$

All paths must be adapted due to the inserted nodes

$$T(\varepsilon) = \varepsilon$$

$$T(L \cdot \Delta) = L \cdot T(\Delta)$$

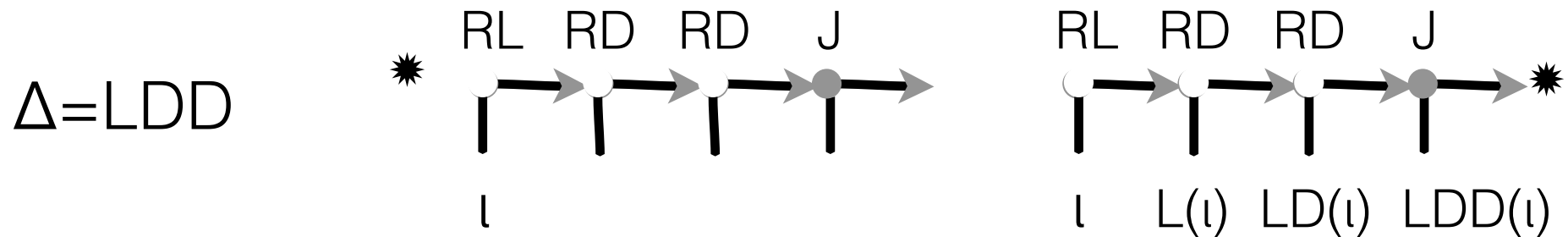
$$T(D \cdot \Delta) = DL \cdot T(\Delta)$$



# Follow the paths

$$\llbracket \Delta_d \cdot \delta \rightarrow \Delta_s \triangleright \Delta_n \rrbracket_l = \text{Comp}(P(l, \Delta_d), P(l, \Delta_s), P(l, \Delta_n))$$

*Read each field and transmit the result to continuation*



$$\text{RD} \triangleq \text{DL} \rightarrow \text{LD} \triangleright \text{D} \quad \text{RL} \triangleq \text{DL} \rightarrow \text{LL} \triangleright \text{D} \quad \text{J} \triangleq \text{L} \rightarrow \text{L} \triangleright \text{D}$$

$$R(\delta \cdot \Delta) = \text{'R}\delta\text{'} \bullet R(\Delta)$$

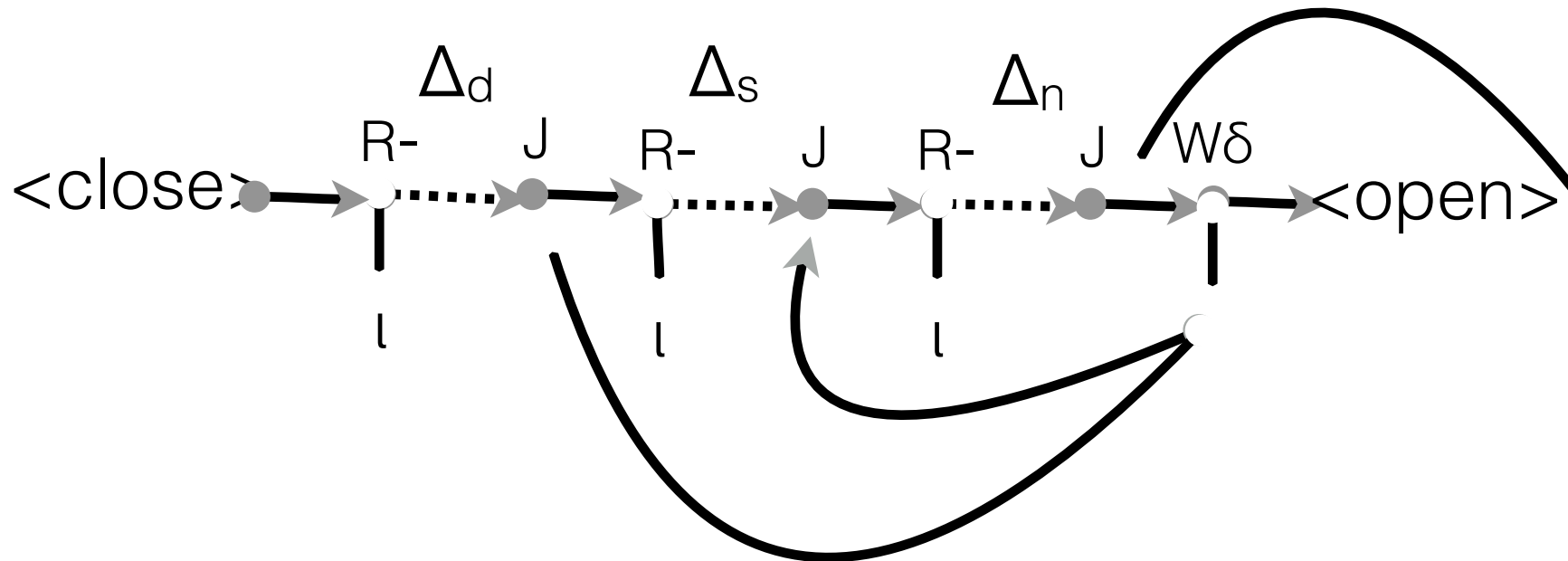
$$R(\varepsilon) = \text{'J'}$$

$$P(l, R(\text{LDD}))$$

$$P(l, \Delta_d) \triangleq \text{SetLight}(l, R(\Delta_d))$$

# Finishing the job

$$\Delta_d \cdot \delta \rightarrow \Delta_s \rightarrow \Delta_n$$

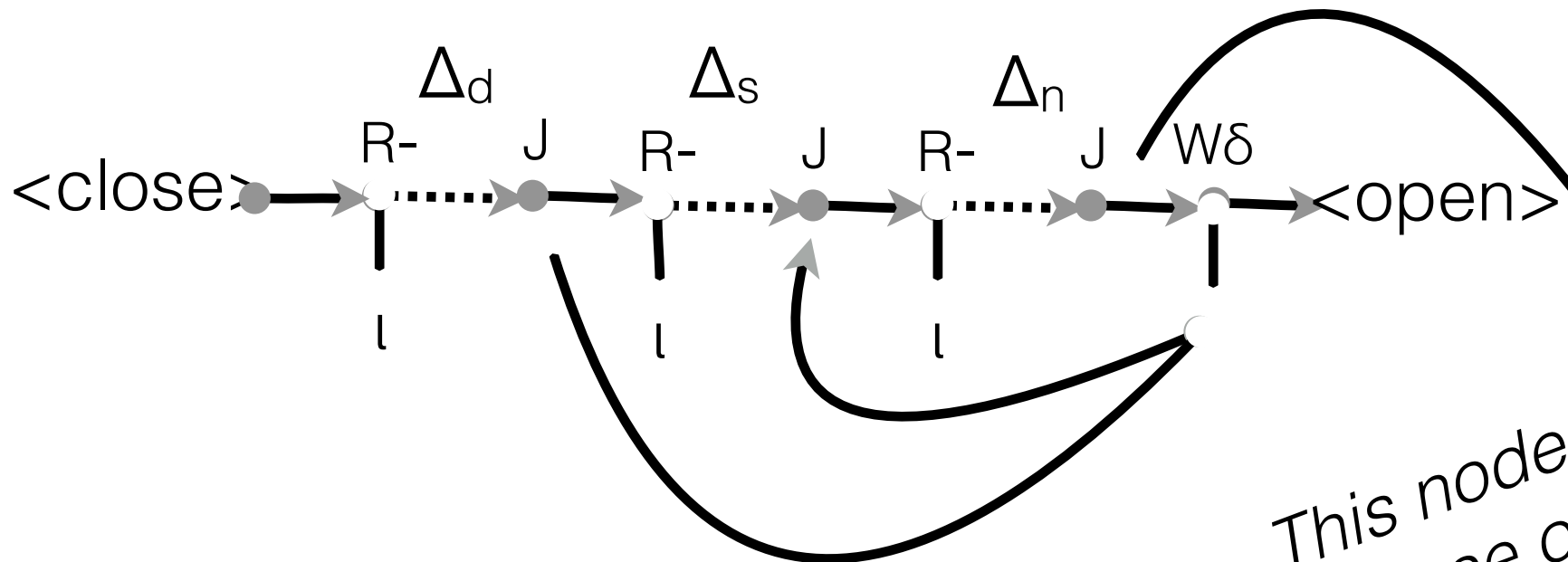


$$WL \triangleq LLLL \rightarrow LD \rightarrow D$$

$$WD \triangleq LLLD \rightarrow LD \rightarrow D$$

# Reducing path length

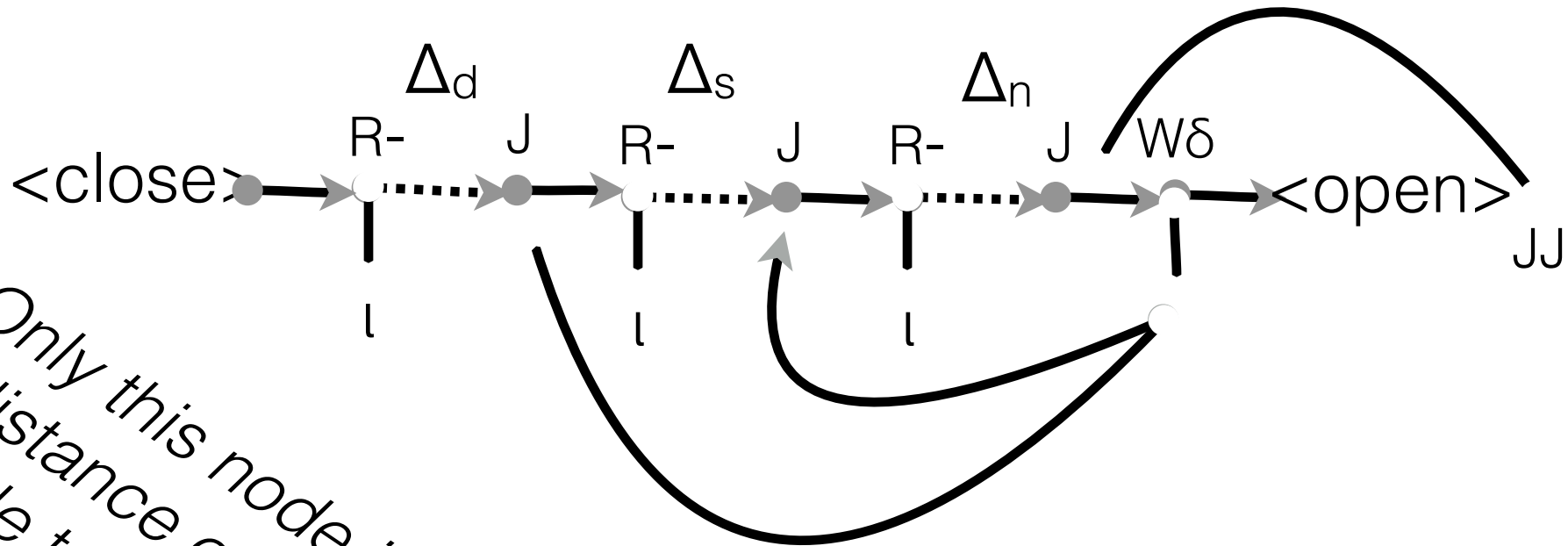
Reducing to paths of length 3 is easy



This node is at a distance of 2 to the node to be modified

# Reducing path length

Reducing to paths of length 2 is challenging

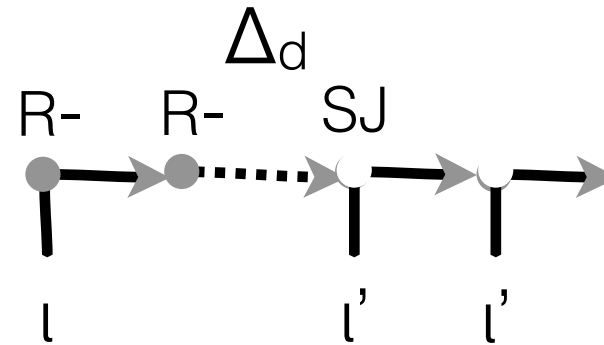
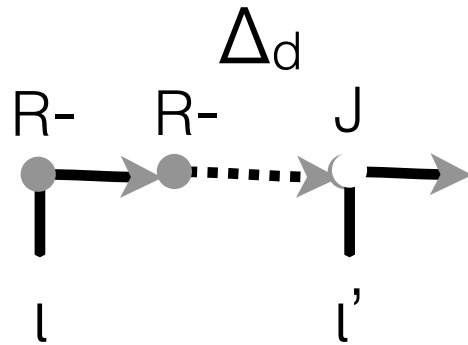


Only this node is at a distance of 1 to the node to be modified

# A fresh place for an instruction

*Locally unused instruction*

SJ  $\triangleq$  DL  $\rightarrow$  L  $\triangleright$  DD

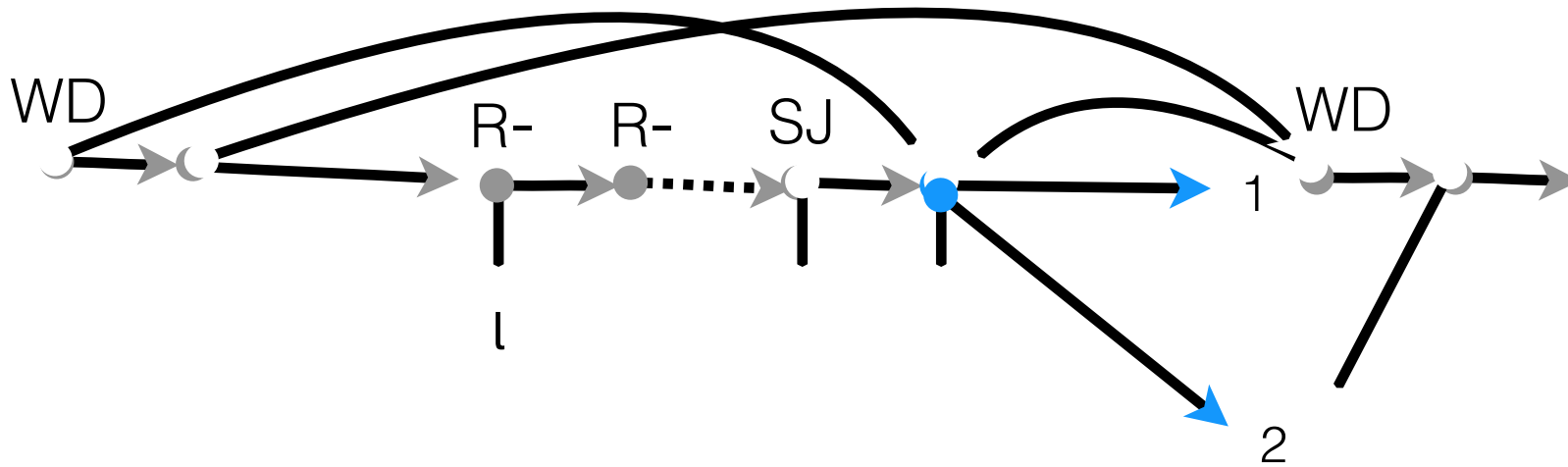


$l'$  is the label of the node to be modified

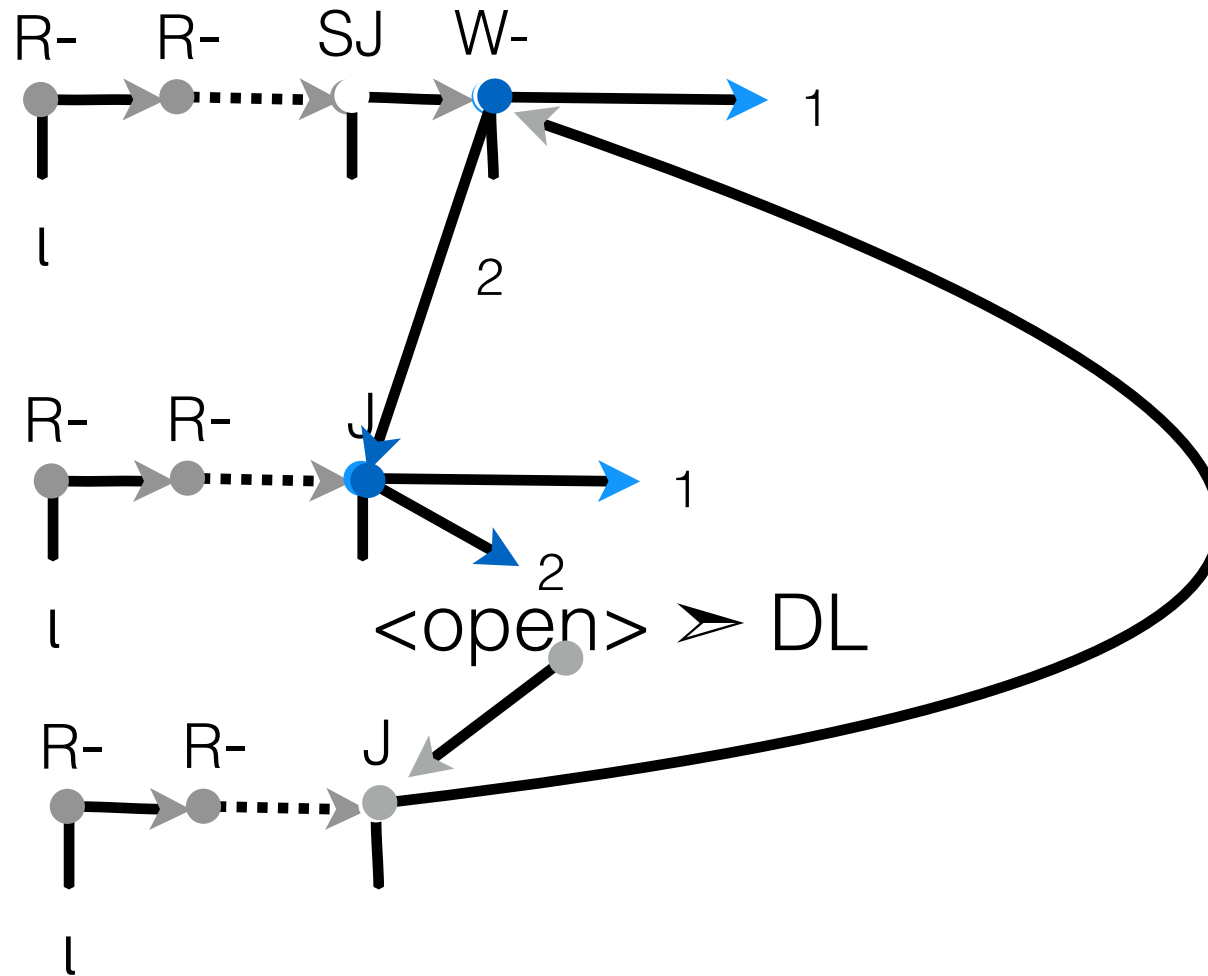
*After path resolution this link can be modified*

# Edge modification afterward

$WD \triangleq LD \blacktriangleright$   $DL \blacktriangleright D$





# Going through the modified path





# Minimal? set of instructions

RL  $\triangleq$  DL  LL  D

RD  $\triangleq$  DL  LD  D

WL  $\triangleq$  LL  DL  D

WD  $\triangleq$  LD  DL  D

SJ  $\triangleq$  DL  L  DD

J  $\triangleq$  L  L  D

Open  $\triangleq$  LLD  DL  DL

Close  $\triangleq$  D  L  D